

Relativistic Quantum Mechanics

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Schedule for today

- What is the smallest dimension of the Dirac equation?
- What is the defining characteristic of a spinor?







Klein-Gordon EQ

Between cosmos & particle physics





Relativistic quantum mechanics



 $[x] = fm = 10^{-12} cm [E] = TeV = 10^{12} eV$



Natural units (
$$\rightarrow \hbar = 1, c = 1$$
):
 $[m] = \text{GeV}$ $[x] = ?$
 $[E] = \text{GeV}$ $[t] = ?$
 $[p] = \text{GeV}$ $[\partial_{\mu}] = ?$

 $\Delta p \cdot \Delta x \gtrsim \hbar \ (\rightarrow uncertainty relation)$



• Most important Eq's to describe particle dynamics: *Klein-Gordon*, *Dirac* Eq.

Relativistic quantum mechanics



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• Solutions:

$$\begin{split} \phi_+(\vec{x},t) &= u(\vec{p}) e^{+i(\vec{p}\vec{x}-Et)} \\ \phi_-(\vec{x},t) &= v(\vec{p}) e^{-i(\vec{p}\vec{x}-Et)} \\ E(\vec{p}) &= \sqrt{m^2 + \vec{p}^2} \end{split} \mbox{ (free wave)}$$

• Peculiarity: Hamiltonian is non-local.

$$\hat{H}_0 = \sqrt{m^2 - \vec{\nabla}^2} = m\sqrt{1 - \frac{\vec{\nabla}^2}{m^2}} = m - \frac{\vec{\nabla}^2}{2m} + \cdots$$
 (*)



• Historical approach by *Paul Dirac 1927*: Find representation of relativistic dispersion relation, which is linear in space time derivatives:

$$i\partial_t \psi = \hat{H}_0 \psi = \left(-i\vec{\alpha}\vec{\nabla} + \beta m\right)\psi$$
• Cannot be pure numbers (*) (\rightarrow algebraic operators).
• Need four independent operators.

• Require Klein-Gordon Eq to be fulfilled for a free Dirac particle:

$$(i\partial_{t})^{2}\psi = \left(-i\vec{\alpha}\vec{\nabla} + \beta m\right)^{2}\psi$$

$$= \left[-\left(\underbrace{\alpha_{i}\alpha_{j} + \alpha_{j}\alpha_{i}}_{(i \leq j)}\right) \underbrace{\partial_{i}\partial_{j}}_{(i \leq j)} - im\left(\underbrace{\alpha_{i}\beta + \beta\alpha_{i}}_{(i \leq j)}\right) \underbrace{\partial_{i} + \left(\beta m\right)^{2}}_{(i \leq j)}\right]\psi \stackrel{!}{=} \left[-\vec{\nabla}^{2} + m\right]\psi$$

$$\{\alpha_{i}, \alpha_{j}\} = 2\delta_{ij} \qquad \{\alpha_{i}, \beta\} = 0 \qquad \beta^{2} = 1 \quad \text{(Anti-commutation relations)}$$

Properties of $\vec{\alpha}$ and β



• Operators $\vec{\alpha}$ and β can be expressed by matrices:

Must be hermitian: \hat{H}_0 should have real *eigenvalues*.



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Must have at least dim=4:

- $\alpha_i^2 = \mathbb{I} \rightarrow$ has only eigenvectors ±1.
- $\beta^2 = \mathbb{I} \to has only eigenvectors \pm 1.$
- Dimension must be even to obtain 0 trace.
- \mathbb{I} + Pauli matrices (\mathbb{I}, σ_i) form a basis of the space of 2×2 matrices. But \mathbb{I} is not traceless (\rightarrow no chance to obtain four independent(!) traceless matrices).
- Simplest representation must at least have dim=4 (can be higher dimensional though).



• Concrete representation of α_i and β matrices:

$$\beta = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \qquad \alpha_i = \begin{pmatrix} 0 & \sigma_i \\ \sigma_i & 0 \end{pmatrix} \qquad (\sigma_i (i = 1, 2, 3) \text{ Pauli matrices})$$

$$\sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$\sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$$

$$\sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$



• Relativistic formulations use γ^{μ} ⁽¹⁾ matrices:

$$\gamma^0 \equiv \beta \qquad \qquad \gamma^i \equiv \beta \alpha_i$$

$$\gamma^0 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \qquad \gamma^i = \begin{pmatrix} 0 & \sigma_i \\ -\sigma_i & 0 \end{pmatrix}$$

$$\{\alpha_i, \alpha_j\} = 2\delta_{ij}$$

$$\{\alpha_i, \beta\} = 0$$

$$[\beta, \beta] = 0$$

$$\{\gamma^{\mu}, \gamma^{\nu}\} = 2g^{\mu\nu}$$

(Compact notation of algebra)

• Dirac equation in mostly known covariant form:

$$(i\gamma^{\mu}\partial_{\mu}-m)\,\psi=0$$

(Dirac Eq)



$$\left(i\gamma^{\mu}\partial_{\mu}-m\right)\psi=0$$

$$\begin{split} \psi_{+}(\vec{x}) &= u(\vec{p})e^{+i(\vec{p}\vec{x}-Et)} \\ \psi_{-}(\vec{x}) &= v(\vec{p})e^{-i(\vec{p}\vec{x}-Et)} \\ & E(\vec{p}) &= \sqrt{m^{2}+\vec{p}^{2}} \\ \\ & \begin{bmatrix} u_{\uparrow}(0) &= \begin{pmatrix} 1\\0\\0\\0 \end{pmatrix} \\ u_{\downarrow}(0) &= \begin{pmatrix} 0\\1\\0\\0\\1 \end{pmatrix} \\ v_{\downarrow}(0) &= \begin{pmatrix} 0\\1\\0\\1\\0 \end{pmatrix} \\ v_{\downarrow}(0) &= \begin{pmatrix} 0\\0\\0\\1\\1 \end{pmatrix} \\ et \operatorname{rest}(\vec{p} \equiv 0) \end{split}$$

(free wave)



$$\left[\left(i\gamma^{\mu}\partial_{\mu}-m\right)\psi=0\right]$$

$$\begin{split} \psi_{+}(\vec{x}) &= u(\vec{p})e^{+i(\vec{p}\vec{x}-Et)} \\ \psi_{-}(\vec{x}) &= v(\vec{p})e^{-i(\vec{p}\vec{x}-Et)} \\ E(\vec{p}) &= \sqrt{m^{2}+\vec{p}^{2}} \\ \downarrow \\ \psi_{-}(\vec{x}) &= v(\vec{p})e^{-i(\vec{p}\vec{x}-Et)} \\ \psi_{-}(\vec{x}) &= v(\vec{x})e^{-i(\vec{p}\vec{x}-Et)} \\ \psi_{-}(\vec{x})e^{-i(\vec{p}\vec{x}-Et)} \\ \psi_{-}(\vec{x})e^{-i(\vec{p}\vec{x}-Et)$$

The transformation behavior of spinors





Classification of physical objects

- In physics we classify objects according to their transformation behavior.
 - (*Lorentz*-)Scalar:
 - (*Lorentz*-)Vector:
 - (*Lorentz-*)Tensor (2. order):
 - (Lorentz-)Spinor: $\Lambda: \psi^{\alpha}(x^{\mu}) \to \psi'^{\alpha}(x'^{\mu}) = S^{\alpha}_{\beta}\psi^{\beta}(\Lambda^{\mu}_{\nu}x^{\nu})$



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Objects composed from spinors



• Observables can be composed of spinors:

 $\overline{\psi}=\psi^{\dagger}\gamma^{0}$ (Adjoint spinor)



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Bosons & Fermions







Satyenda Nath Bose (*1. January 1894, † 4. February 1974)

Enrico Fermi (*29. September 1901, † 28. November 1954)

Bosons	Fermions	Karlsruhe Institute of Technology
$\left(\partial_{\mu}\partial^{\mu} + m^2\right)\phi = 0$	$\left(i\gamma^{\mu}\partial_{\mu}-m\right)\psi=0$	
• Integer spin 0, 1, ⁽²⁾	• Half-integer spin ½, ⁽²⁾	

• Commutator relations [. , .].

• Anti-commutator relations { . , . }.





- Brief reprise of main relativistic equations of quantum mechanics.
- Klein-Gordon equation to describe kinematics of bosons.
- Dirac equation to describe kinematics of fermions.
- Main tool box to go from field theoretical calculations to observable behavior of particles.
- From next lecture on go one level up \rightarrow field theoretical level.
- Prepare "The Higgs Boson Discovery at the Large Hadron Collider" Section 2.1.





• The following 16 matrices form a basis of the 4×4 matrices:



- Orthonormal (with scalar product $< .|. > = \frac{1}{4}Tr(. \cdot .)$).
- All matrices traceless apart from $\mathbb{I}_4.$